



Start

1. Fast Pace (18)
2. Normal Pace (19)
3. HALT – Turn Right
1 Step- Call to Heel,
HALT (104)
4. Moving Side Step
Right (20)
5. 270 Left Turn (10)

6. HALT – Stand –
Walk Around Dog
(105)
7. About “U” Turn (8)
8. 270 Right Turn (9)
9. Send Over Jump –
Handler Passes By
(103)

10. Left Turn (6)
11. HALT – Call Front
– Finish Right
HALT(110)
12. Left Turn (6)
13. Offset Serpentine
Right (41)

Finish